# Verifying Reliable Sessions Over an Unreliable **Network in Distributed Separation Logic**

**The Second Iris Workshop** 

Léon Gondelman & Jonas Kastberg Hinrichsen

May 2, 2022

# I. Reliable Communication in Distributed Systems

- Network communication & message-passing concurrency:

  - > communication protocols and resource transfer play central role

# **Communicating processes**

> coordination is done via exchanging messages (not via shared memory)



- - > messages arrive from one machine to another with a certain delay

# **Fundamental Difference**

Communication over the network is fundamentally unreliable and asynchronous:

> messages are lost, arrive out of order, got duplicated, or forged by adversary

> network partitions make it impossible to distinguish, in a finite amount of time, between delayed messages and lost messages (e.g. due to remote's crash)





- Transport layer protocols such as TCP, SCTP and others provide some reliability guarantees (at-most-once in-order delivery).
- However, no protocol can guarantee that messages will arrive in-order & without duplicates exactly once.
- In the presence of network partitions/broken connections, TCP is no better than UDP: *in fine*, reliability is achieved at the application level.
- Many reasons to build fault-tolerance on top of UDP: > gaming community, Google QUIC (2013), Ensemble (Haiden 98)

# **Fault Tolerance**



#### • Two research directions:

- map-reduce, deadlock freedom, op-based CRDTs, ...
- > **Model** network with faults to build fault-tolerance:
- Longstanding goal: a unified framework where high-level abstractions meet realistic fault-tolerant implementations.
- The story of this work: one step towards this goal.

# **Verification Perspective**

> Assume fault-tolerance to reason about high-level problems/algorithms:

consensus algorithms, reliable causal broadcast, client-server sessions.



Actris Session Type-based Reasoning

> provides a high-level model of reliable communication (Actris Ghost Theory)

where the communication layer itself is reliable.

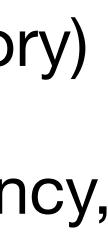
$$\begin{cases} c \rightarrow \mathbf{!} \, \vec{x} : \vec{\tau} \, \langle v \rangle \{P\}. \, \text{prot} * P[\vec{t}/\vec{x}] \} \\ \text{send} \, c \, (v[\vec{t}/\vec{x}]) \\ \{ c \rightarrow \text{prot}[\vec{t}/\vec{x}] \} \end{cases}$$

# Key Observation (1/2)

> has been applied so far only to reason about message-passing concurrency,

$$\{c \mapsto ?\vec{x} : \vec{\tau} \langle v \rangle \{P\}. \ prot \}$$
  
recv c  
$$\{w. \exists (\vec{y} : \vec{\tau}). \ (w = v[\vec{y}/\vec{x}]) *$$
  
$$P[\vec{y}/\vec{x}] * c \mapsto prot[\vec{y}/\vec{x}]$$



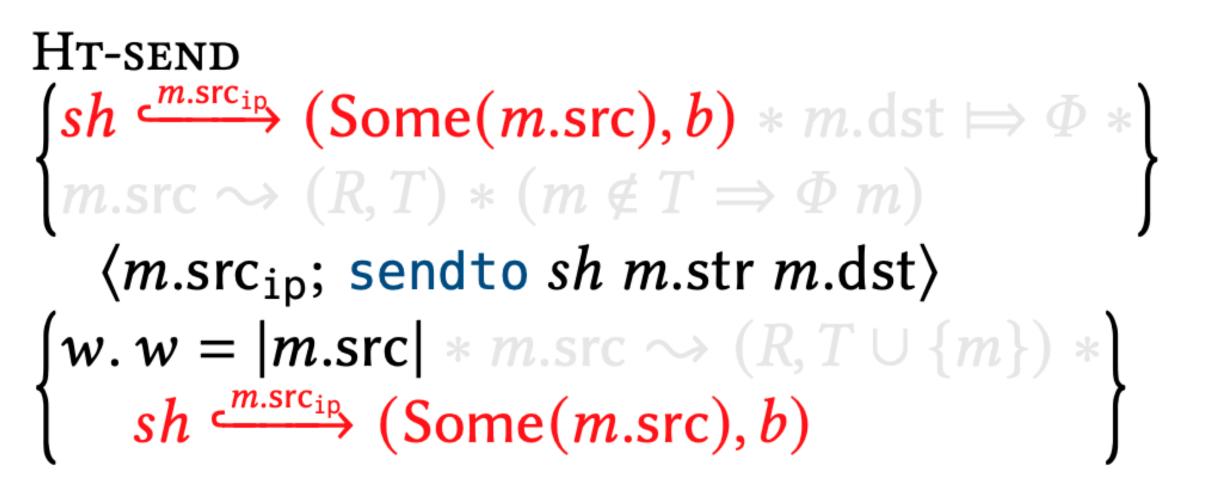




Aneris Distributed Separation Logic

> provides rules to reason about unreliable unconnected communication;

> had no native/library support for reliable/connected communication (i.e. each time reliability/sessions had to be built in ad-hoc way).



# **Key Observation (2/2)**

HT-RECV  

$$\begin{cases} sh \stackrel{sa_{ip}}{\longrightarrow} (\text{Some}(sa), b) * sa \rightarrow (R, T) * sa \models \\ \langle sa_{ip}; \text{ receivefrom } sh \rangle \\ \\ \{w. sh \stackrel{sa_{ip}}{\longrightarrow} (\text{Some}(sa), b) * \\ (b = \text{false} * w = \text{None} * sa \rightarrow (R, T)) \\ (\exists m. w = \text{Some} (m.\text{str}, m.\text{src}) * m.\text{dst} = \\ sa \rightarrow (R \cup \{m\}, T) * (m \notin R \Rightarrow \Phi) \end{cases}$$

(a) socket handle resource  $sh \stackrel{sa_{ip}}{\longrightarrow} (Some(sa), b)$ 





Aneris Distributed Separation Logic

> provides rules to reason about unreliable unconnected communication;

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HT-SEND  $\begin{cases} sh \stackrel{m.\operatorname{src}_{\operatorname{ip}}}{\longrightarrow} (\operatorname{Some}(m.\operatorname{src}), b) * m.\operatorname{dst} \mapsto \Phi * \\ m.\operatorname{src} \rightsquigarrow (R, T) * (m \notin T \Rightarrow \Phi m) \end{cases} \end{cases}$ (m.src<sub>ip</sub>; sendto sh m.str m.dst)  $\begin{cases} w. w = |m.src| * m.src \rightsquigarrow (R, T \cup \{m\}) * \\ sh \stackrel{m.src_{ip}}{\longrightarrow} (Some(m.src), b) \end{cases}$ 

(b) message history resources  $sa \sim (R, T)$ 

# Key Observation (2/2)

HT-RECV  

$$\begin{cases} sh \stackrel{sa_{ip}}{\longrightarrow} (\text{Some}(sa), b) * sa \rightsquigarrow (R, T) * sa \\ \langle sa_{ip}; \text{ receivefrom } sh \rangle \\ \\ \{w. sh \stackrel{sa_{ip}}{\longrightarrow} (\text{Some}(sa), b) * \\ (b = \text{false} * w = \text{None} * sa \rightsquigarrow (R, T)) \\ (\exists m. w = \text{Some} (m.\text{str}, m.\text{src}) * m.\text{dst} = \\ sa \rightsquigarrow (R \cup \{m\}, T) * (m \notin R \Rightarrow \Phi) \end{cases}$$





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(c) socket protocol predicate  $sa \mapsto \Phi$ 

# **Key Observation (2/2)**

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 $\Rightarrow \Phi$ V = sa \*

# Let Aneris and Actris projects meet to enable reasoning about reliable network communication!

...The rendez-vous point is our verified client-server library.

# **Our idea**

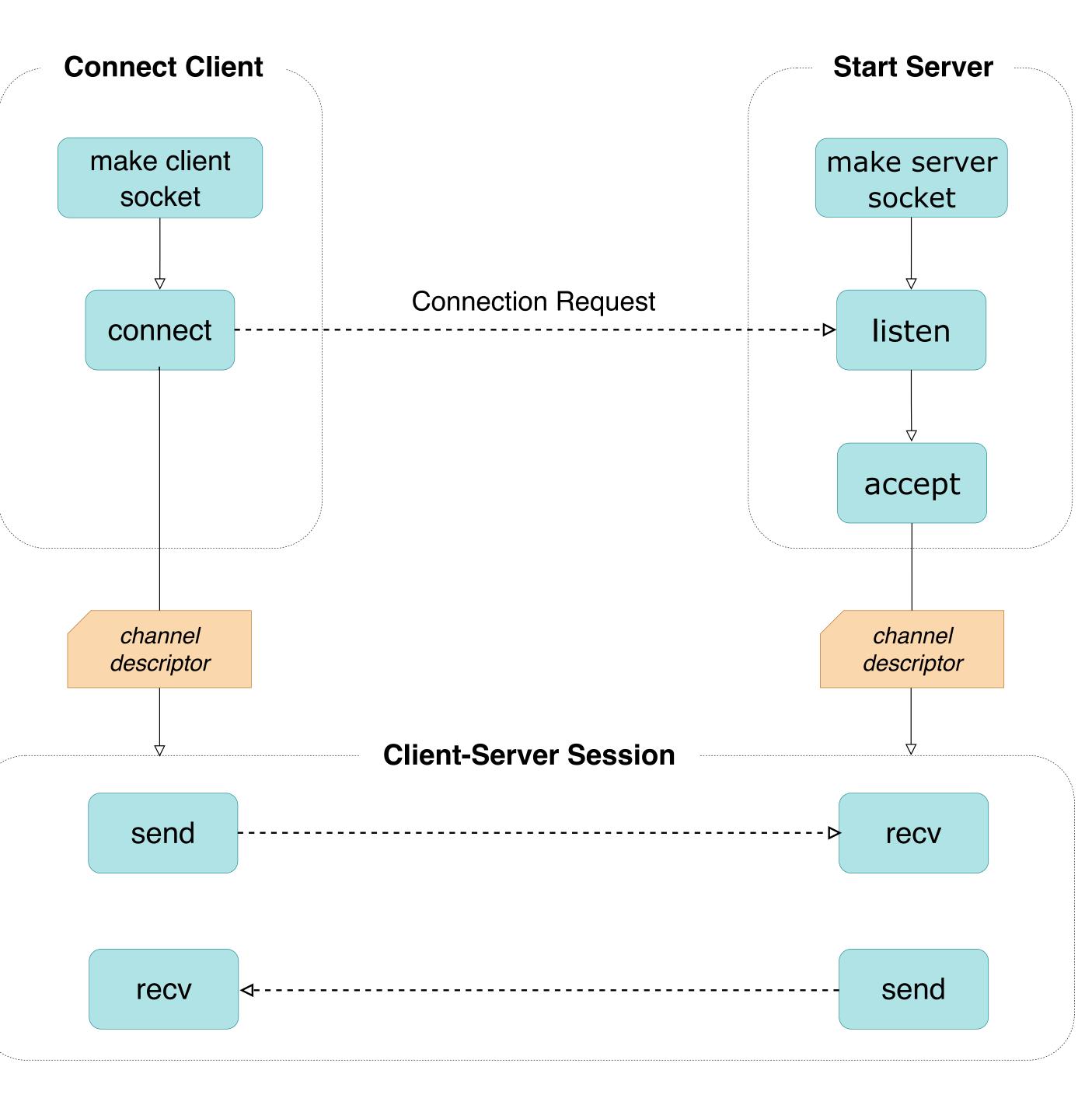


# **II. The API of the library**

# **Our Library**

- BSD sockets-like primitives
- 4-handshake connection
- buffered bidirectional channels
- sequence-ids/acknowledgments/ retransmission mechanisms
- ~ 350 lines of OCaml

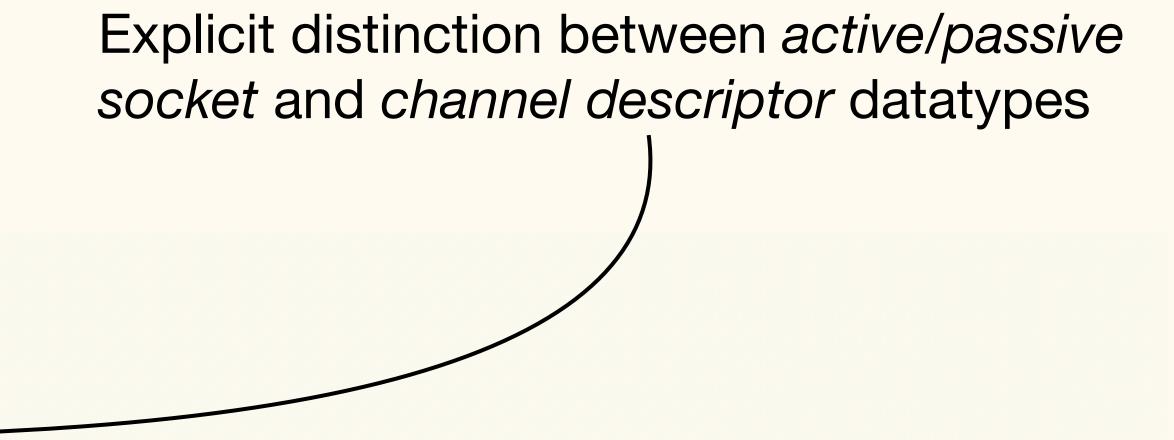
- distinction between active/passive sockets and channels
- data transfer of serialisable values



#### open Ast

type ('a, 'b) client\_skt type ('a, 'b) server\_skt type ('a, 'b) chan\_descr val server\_listen : ('a, 'b) server\_skt -> unit val accept : ('a, 'b) server\_skt -> ('a, 'b) chan\_descr \* saddr val connect : ('a, 'b) client\_skt -> saddr -> ('a, 'b) chan\_descr val send : ('a, 'b) chan\_descr -> 'a -> unit val try\_recv : ('a, 'b) chan\_descr -> 'b option val recv : ('a, 'b) chan\_descr -> 'b

## **OCaml API**



val make\_client\_skt : 'a serializer -> 'b serializer -> saddr -> ('a, 'b) client\_skt val make\_server\_skt : 'a serializer -> 'b serializer -> saddr -> ('a, 'b) server\_skt

#### How **client** serialises values to be send to the **server**

open Ast

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## **OCaml API**

How **server** deserialises values received from the client

val make\_client\_skt : 'a serializer -> 'b serializer -> saddr -> ('a, 'b) client\_skt val make\_server\_skt : 'a serializer -> 'b serializer -> saddr -> ('a, 'b) server\_skt

#### How **server** serialises values to be send to the **client**

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### **OCaml API**

#### How **client** deserialises values received from the server

val make\_client\_skt : 'a serializer -> 'b serializer -> saddr -> ('a, 'b) client\_skt val make\_server\_skt : 'a serializer -> 'b serializer -> saddr -> ('a, 'b) server\_skt

```
open Ast
open Serialization_code
open Client_server_code
let int_s = int_serializer
let str_s = string_serializer
let rec echo_loop c =
  let req = recv c in
  send c (strlen req);
  echo_loop c
let accept_loop s =
  let rec loop () =
    let c = fst (accept s) in
    fork echo_loop c; loop ()
  in loop ()
let server srv =
  let s = make_server_skt int_s str_s srv in
  server_listen s;
  fork accept_loop s
```

## **Example: echo server**

#### let client clt srv s1 s2 = let s = make\_client\_skt str\_s int\_s clt in let c = connect s srv insend c s1; send c s2; let m1 = recv c inlet m2 = recv c inassert (m1 = strlen s1 && m2 = strlen s2)

#### let client\_0 clt srv = client clt srv "carpe" "diem"



# **III. Specification**

#### **User Parameters:**

UserParams ≜ {srv : Address; srv\_ser : Serialization;}
prot : iProto; clt\_ser : Serialization;

#### **Session Resources:**

SessionResources(UP : UserParams)  $\triangleq$ 

srv_si	: Message $\rightarrow$ iProp;	Can
SrvInit	: iProp;	$C > \frac{i_1}{se}$
CanListen : Val $\rightarrow$ iProp;		laws
Listens	: Val $\rightarrow$ iProp;	

#### Notations :

# **Spec (1/4): Parameters & Resources**

Connect : Val  $\rightarrow$  Address;  $\rightarrow$  iProp;  $\xrightarrow{ip}_{vr} ! \vec{x} : \vec{\tau} \langle v \rangle \{P\}. prot (mapsto connective);$ s about those resources (e.g. subprotocols)

S := SessionResources(UP), S.srv := UP.srv





#### **Client Setup:**

#### HT-MAKE-CLIENT-SOCKET {FreeAddr(*clt*) \* *clt* $\rightarrow$ ( $\emptyset$ , $\emptyset$ ) \* *clt* $\neq$ **S.srv** } $\langle clt_{ip}; mk_clt_skt (S.srv_ser) (S.clt_ser) clt \rangle$ $\{w. \exists skt. w = skt * S.CanConnect clt skt\}$

**Server Setup:** 

HT-MAKE-SERVER-SOCKET FreeAddr(S.srv) \* S.srv  $\rightarrow$  ( $\emptyset, \emptyset$ ) \* $S.srv \Rightarrow S.srv_si * S.SrvInit$ (S.srv<sub>ip</sub>; mk\_srv\_skt S.srv\_ser S.clt\_ser S.srv)  $\{w. \exists skt. w = skt * S.CanListen skt\}$ 

Нт-ассерт  $\{S.Listens \, skt\} \, \langle S.srv_{ip}; \, accept \, skt \rangle \, \{w. \exists c. w = (c, sa) * S.Listens \, skt \ * c \ \xrightarrow{S.srv_{ip}}{S.srv \, ser} \, \overline{S.prot} \}$ 

# Spec (2/4): Client/Server Setup

HT-CONNECT {S.CanConnect clt skt}  $\langle clt_{ip}; connect \, skt \, S.srv \rangle$  $\{w. \exists c. w = c * c \xrightarrow{clt_{ip}} S.prot\}$ 

HT-LISTEN {S.CanListen skt}  $\langle S.srv_{ip}; listen skt \rangle$ {S.Listens skt}





#### **Client Setup:**

HT-MAKE-CLIENT-SOCKET {FreeAddr(*clt*) \* *clt*  $\rightarrow$  ( $\emptyset$ ,  $\emptyset$ ) \* *clt*  $\neq$  **S.srv** } (clt<sub>ip</sub>; mk\_clt\_skt (S.srv\_ser) (S.clt\_ser) clt)  $\{w. \exists skt. w = skt * S.CanConnect clt skt\}$ 

### **Server Setup:**

**HT-MAKE-SERVER-SOCKET**  $\begin{cases} \mathsf{FreeAddr}(S.\mathsf{srv}) * S.\mathsf{srv} \rightsquigarrow (\emptyset, \emptyset) * \\ S.\mathsf{srv} \vDash S.\mathsf{srv}_\mathsf{si} * S.\mathsf{SrvInit} \end{cases} \end{cases}$ (S.srv<sub>ip</sub>; mk\_srv\_skt S.srv\_ser S.clt\_ser S.srv)  $\{w. \exists skt. w = skt * S.CanListen skt\}$ 

HT-ACCEPT

 $\{S.Listens \, skt\} \, \langle S.srv_{ip}; accept \, skt \rangle \, \{w. \exists c. w = (c, sa) * S.Listens \, skt \, * c > S.srv_{ip}, S.srv_{ip} \}$ 

# Spec (2/4): Client/Server Setup

HT-CONNECT {S.CanConnect clt skt}  $\langle clt_{ip}; connect \, skt \, S.srv \rangle$  $\{w. \exists c. w = c * c \xrightarrow{clt_{ip}} S.prot\}$ 

HT-LISTEN {S.CanListen skt}  $\langle S.srv_{ip}; listen skt \rangle$ {S.Listens skt}





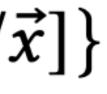
# HT-RELIABLE-RECV

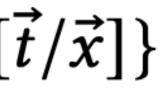
# HT-reliable-send

# **Spec (3/4): Reliable Data Transfer**

 $\{c \xrightarrow{ip}_{ser} ?\vec{x}: \vec{\tau} \langle v \rangle \{P\}. \ prot\} \langle ip; \ recv \ c \rangle \{w. \exists \vec{y}. \ w = v[\vec{y}/\vec{x}] * c \xrightarrow{ip}_{ser} prot[\vec{y}/\vec{x}] * P[\vec{y}/\vec{x}]\}$ 

 $\left\{c \xrightarrow{ip}_{ser} ! \vec{x} : \vec{\tau} \langle v \rangle \{P\}. \ prot \ * \ P[\vec{t}/\vec{x}] \ * \ Ser \ ser \ (v[\vec{t}/\vec{x}]) \right\} \langle ip; \ send \ c \ (v[\vec{t}/\vec{x}]) \rangle \ \{c \xrightarrow{ip}_{ser} \ prot[\vec{t}/\vec{x}]\}$ 



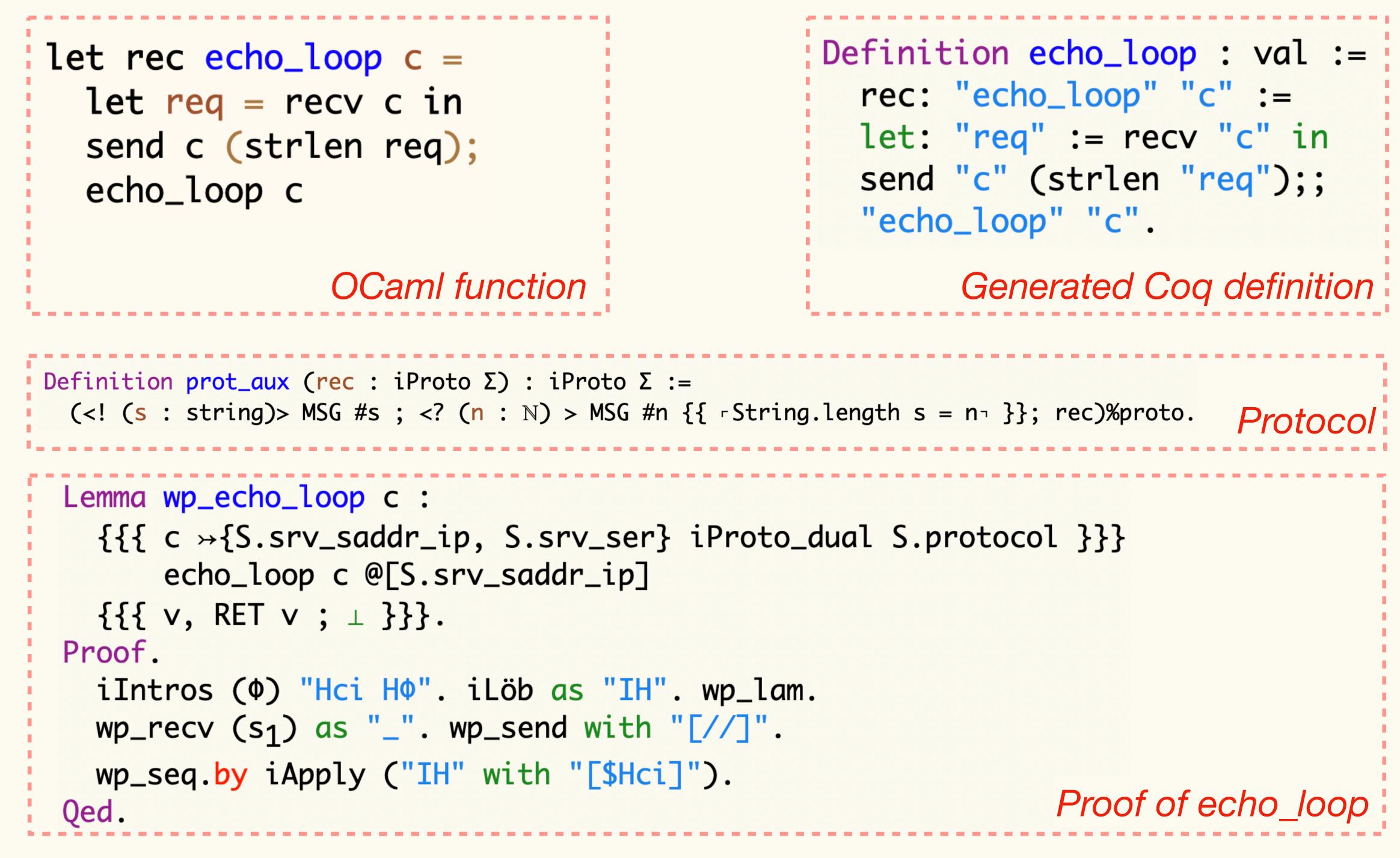


INIT-SETUP True  $\Rightarrow \exists S : SessionResources(UP).$ S.SrvInit \*

# Spec (4/4) : Logical Setup

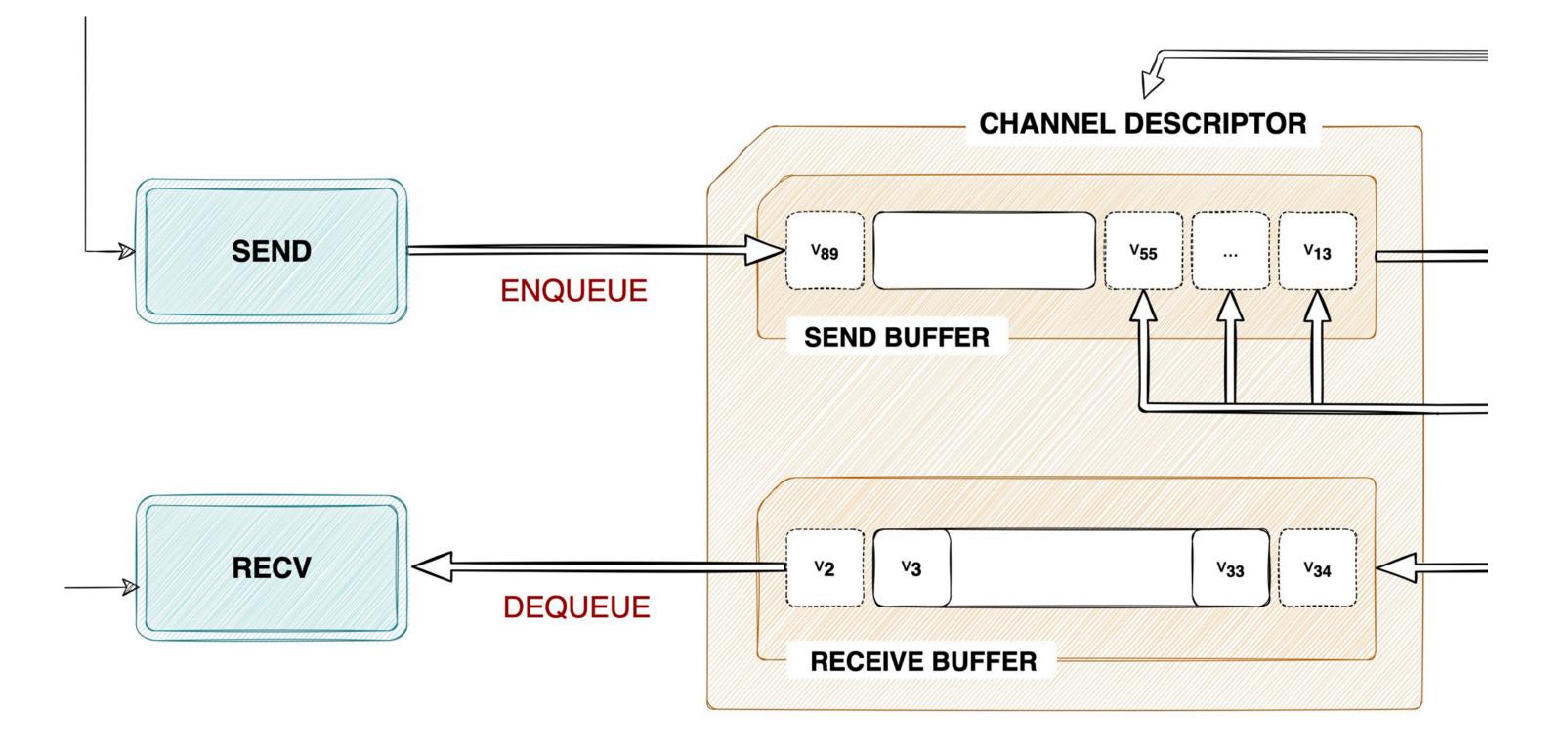
- $(\forall sa, HT-MAKE-CLIENT-SOCKET S](sa)) *$ HT-MAKE-SERVER-SOCKET S \* $(\forall skt sa, HT-CONNECT[S](skt, sa)) *$ (specs for listen, accept, send, recv, try\_recv)





# **IV. Verification**

- The implementation of send and recv is the same for client and server. In fact, their implementation is also **agnostic of network**.



# Anatomy of send & recv

 This is possible because channels are using in- and out- buffers as indirection (calling send enqueues to the out-buffer, calling recv dequeues from the in-buffer)





Crucially, this is also where the *connection* between **Actris Ghost Theory** and the **implementation** takes place. However, this connection is not immediate :

the two Actris logical buffers

> describe symmetrically for each direction the messages in transit > are governed (inside an Iris invariant) by the shared resource prot\_ctx  $\chi \vec{v_1} \vec{v_2}$ 

the four physical buffers

> are local data of each node and are updated asynchronously

# The rendez-vous point

- > play different role (out-buffer simply (re)transmits, in-buffer keeps data for delivery)



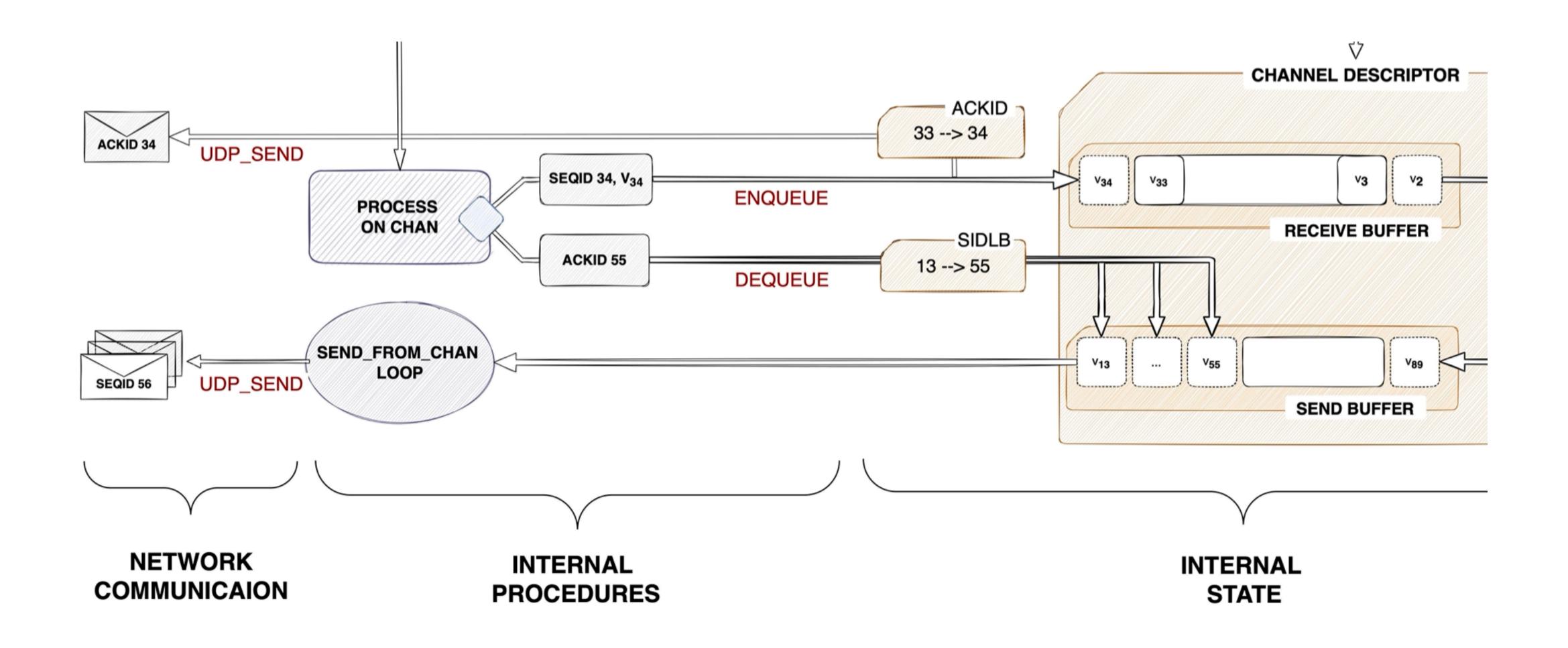


- Our solution is to introduce additional logical buffers TI, RI, Tr, Rr as a glue. (TI, Tr) describe the **history of sent** messages; (RI, Rr) describe the history of received messages (by the application).
- Various relations must hold between Actris, glue, and physical buffers:
  - (Internal-Coh) (Actris-Coh) (SBuf-Coh)
  - v1 = TI Rr and v2 = Tr RI
  - Rr is prefix of TI and RI is prefix of Tr sbufl is suffix of TI and sbufr is suffix of Tr
  - rbufl is prefix of (Tr RI) and rbufr is prefix of (TI Rr)(Rbuf-Coh)
- The verification is then primarily an effort in preserving these relations, in the presence of the concurrent accesses of the communication layer.

# More buffers, seriously?



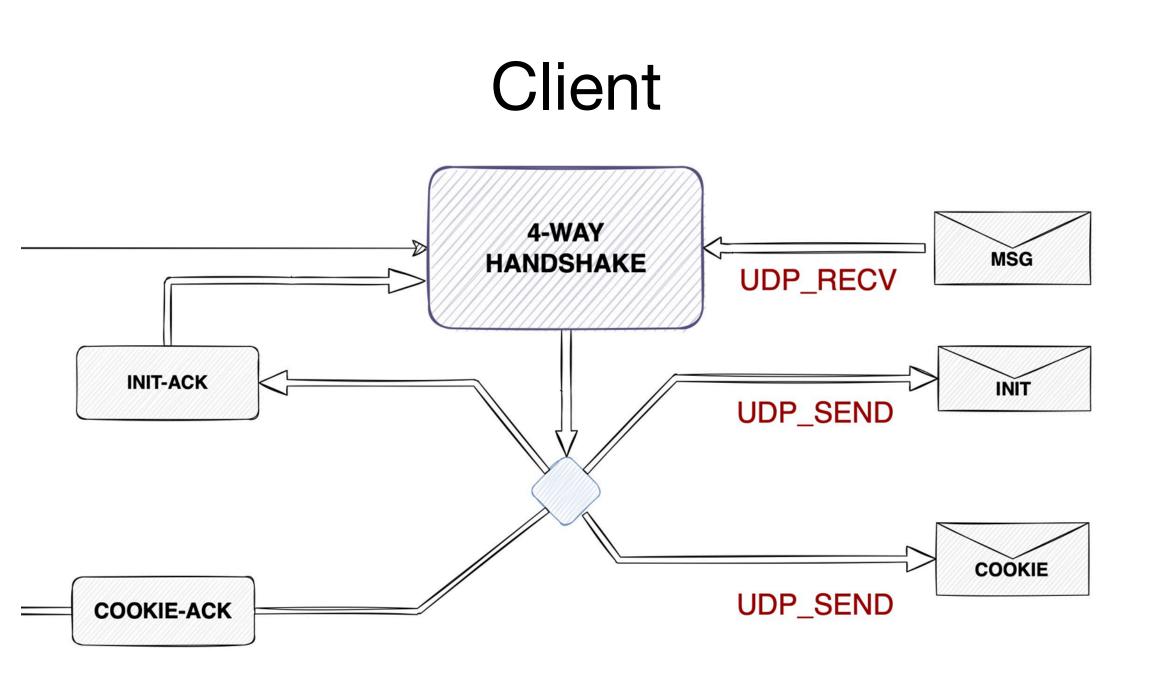
the same for clients and servers, and so are our proofs.



# **Other Observations (1/3)**

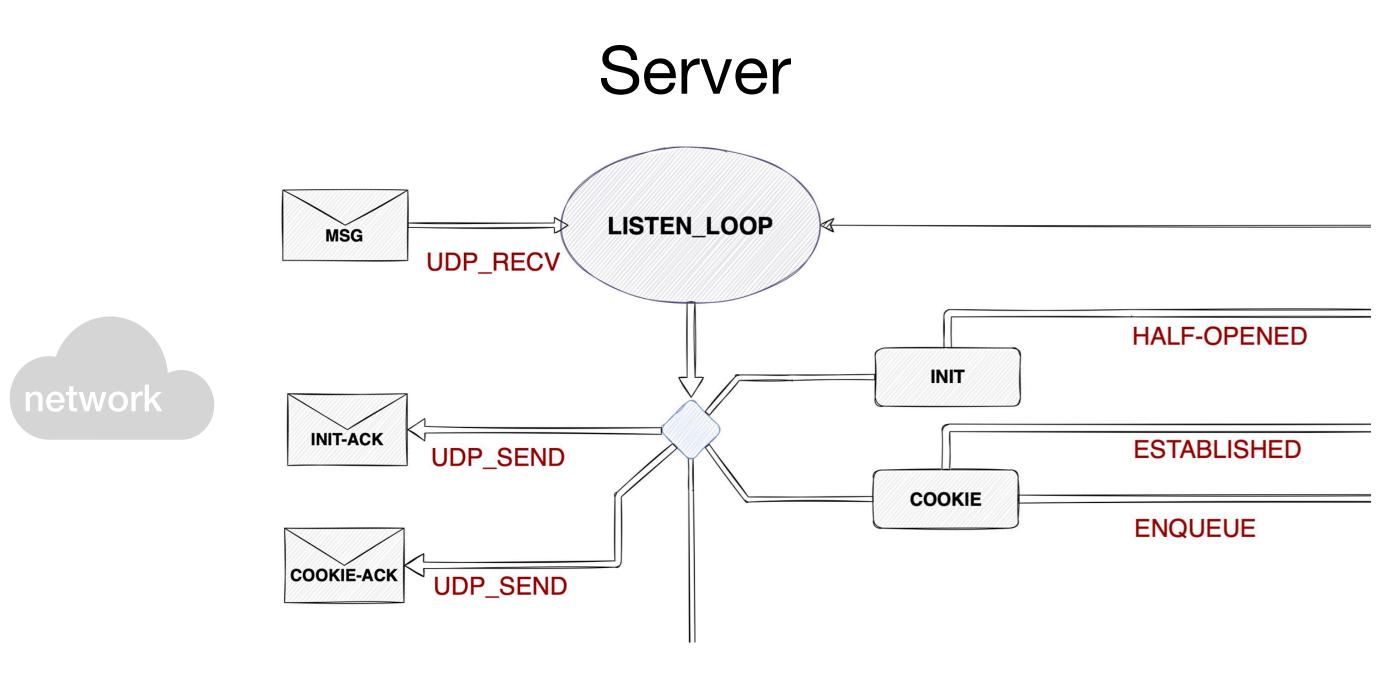
• The internal procedures that enforce the fault-tolerance are also (mostly)





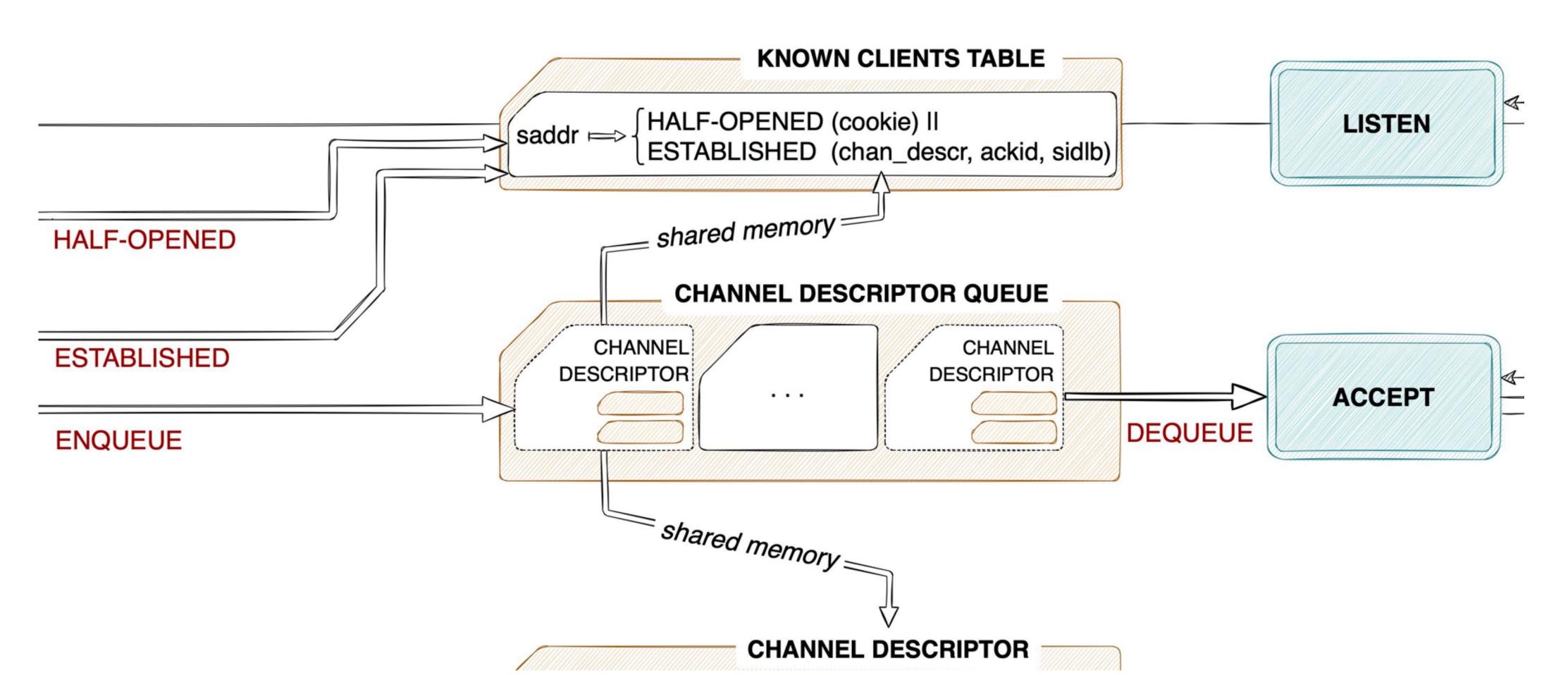
# **Other Observations (2/3)**

 The 4-handshake is different for each side and requires some effort in verification as it encodes an STS with several edge and absurd cases.





and a **channel description queue** for the established connections.

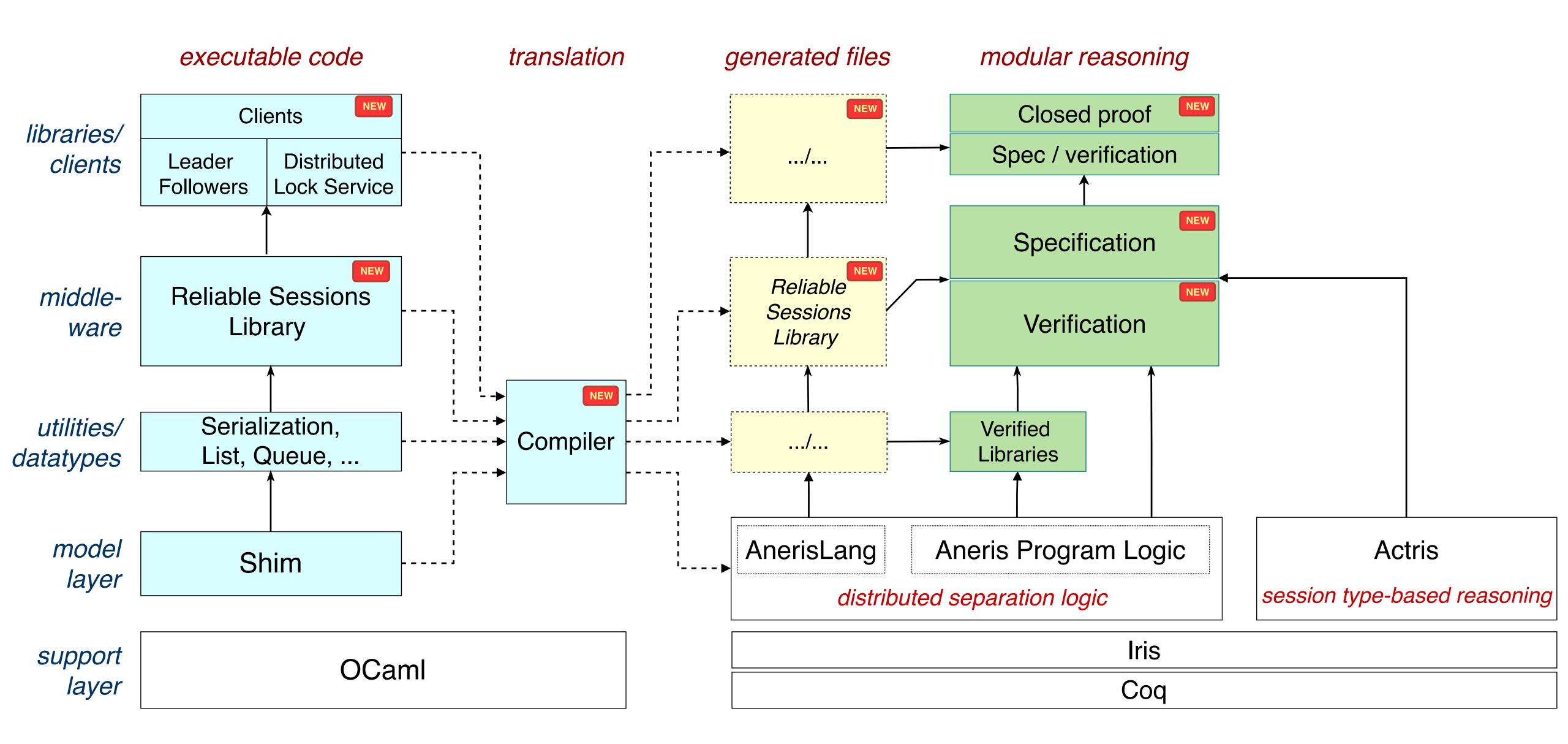


# **Other Observations (3/3)**

• The implementation/verification of server side is more difficult, because the server must maintain a table of known clients with their connection state



# V. Conclusion & Future Directions



# Contributions



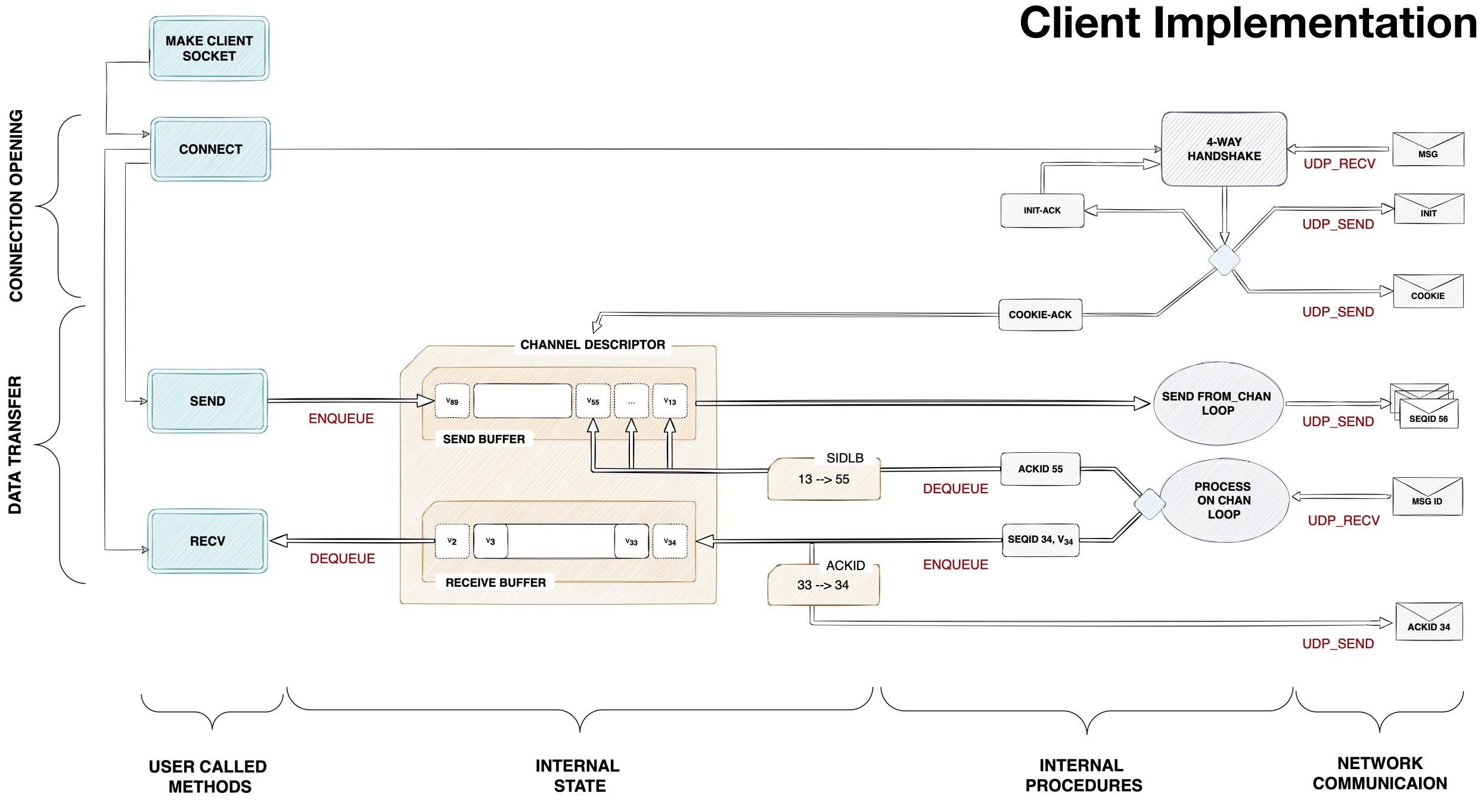
- Graceful/Abrupt session ending : detectable connection failures, reconnection
- Cryptography/Security: 4-way handshake procedure / authentification / QUIC
- Network Partitions : group membership/consensus built on top of our library
- Group Communication : client-service communication
- Transparency : verified libs for distributed/multithreaded programs (e.g. Functory)
- (and maybe your insights/ideas !)

# **Possible Future Directions**



# Thank you !

# **Backup slides**



















### **Server Implementation**

