Predictable, efficient, and extensible Iris automation with Lithium



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Key idea of Lithium / RefinedC

(1) Identify a subset of separation logic that can be automated using goal-directed proof search without backtracking

Atom
$$A ::= v \triangleleft_{\mathsf{v}} \tau \mid \dots$$

Basic goal $F ::= \vdash_{\mathsf{STMT}}^{\Sigma} s \mid A_1 <: A_2 \{G\} \mid \dots$
Goal $G ::= \mathsf{True} \mid F \mid H * G \mid H \twoheadrightarrow G \mid G_1 \wedge G_2 \mid \forall x. \ G(x) \mid \exists x. \ G(x)$
Left-goal $H ::= \phi \mid A \mid H * H \mid \exists x. \ H(x)$
Contexts $\Gamma ::= \emptyset \mid \Gamma, x \mid \Gamma, \phi \qquad \Delta ::= \emptyset \mid \Delta, A$

(2) Reduce the of verification complex programs to the Lithium fragment via **high-level abstractions**

Automating disjunction

 $P \vee Q$

Introduction:

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Elimination:

7

Automating disjunction

 $v \triangleleft_{\mathsf{v}} \phi @ \operatorname{optional}(\&_{\mathsf{own}}(\tau), \mathsf{null}) \triangleq \phi * v \triangleleft_{\mathsf{v}} \&_{\mathsf{own}}(\tau) \vee \neg \phi * v \triangleleft_{\mathsf{v}} \mathsf{null}$

Introduction:

Elimination:

```
O-OPTIONAL-EQ \frac{(\lceil \phi \rceil \twoheadrightarrow v_1 \rightsquigarrow \&_{\text{own}}(\tau) \twoheadrightarrow G(\text{false}, \text{False @ bool})) \land (\lceil \neg \phi \rceil \twoheadrightarrow G(\text{true}, \text{True @ bool}))}{\vdash_{\text{BINOP}} (v_1 : \phi \text{ @ optional}(\&_{\text{own}}(\tau), \text{null})) = (v_2 : \text{null}) \{v, \tau. G(v, \tau)\}}
```

Automating invariants

```
v \triangleleft_{\mathsf{V}} \mathsf{atomicbool}(H_\top, H_\bot) \triangleq \exists \ell. \, v = \ell * \left[ \exists b. \, \ell \mapsto b * (b \, ? \, H_\top : H_\bot) \right]^\mathcal{N}
```

```
CAS-BOOL (v_2 \triangleleft_v \&_{own}(\neg b_1 @ bool) * G(false, False @ bool)) \land \\ \underline{((b_1?H_\top:H_\bot) * (b_2?H_\top:H_\bot) * (v_2 \triangleleft_v \&_{own}(b_1 @ bool) * G(true, True @ bool)))} \\ \vdash_{CAS} CAS(v_1: atomicbool(H_\top,H_\bot), v_2: \&_{own}(b_1 @ bool), v_3: b_2 @ bool) \{v, \tau. G(v, \tau)\}
```

Questions?



- (1) goal-directed proof search without backtracking
- (2) guide proof via high-level abstractions

```
Atom A ::= v \triangleleft_{\mathsf{v}} \tau \mid \dots

Basic goal F ::= \vdash_{\mathsf{STMT}}^{\Sigma} s \mid A_1 <: A_2 \{G\} \mid \dots

Goal G ::= \mathsf{True} \mid F \mid H * G \mid H \twoheadrightarrow G \mid G_1 \wedge G_2 \mid \forall x. \ G(x) \mid \exists x. \ G(x)

Left-goal H ::= \phi \mid A \mid H * H \mid \exists x. \ H(x)

Contexts \Gamma ::= \emptyset \mid \Gamma, x \mid \Gamma, \phi \qquad \Delta ::= \emptyset \mid \Delta, A
```